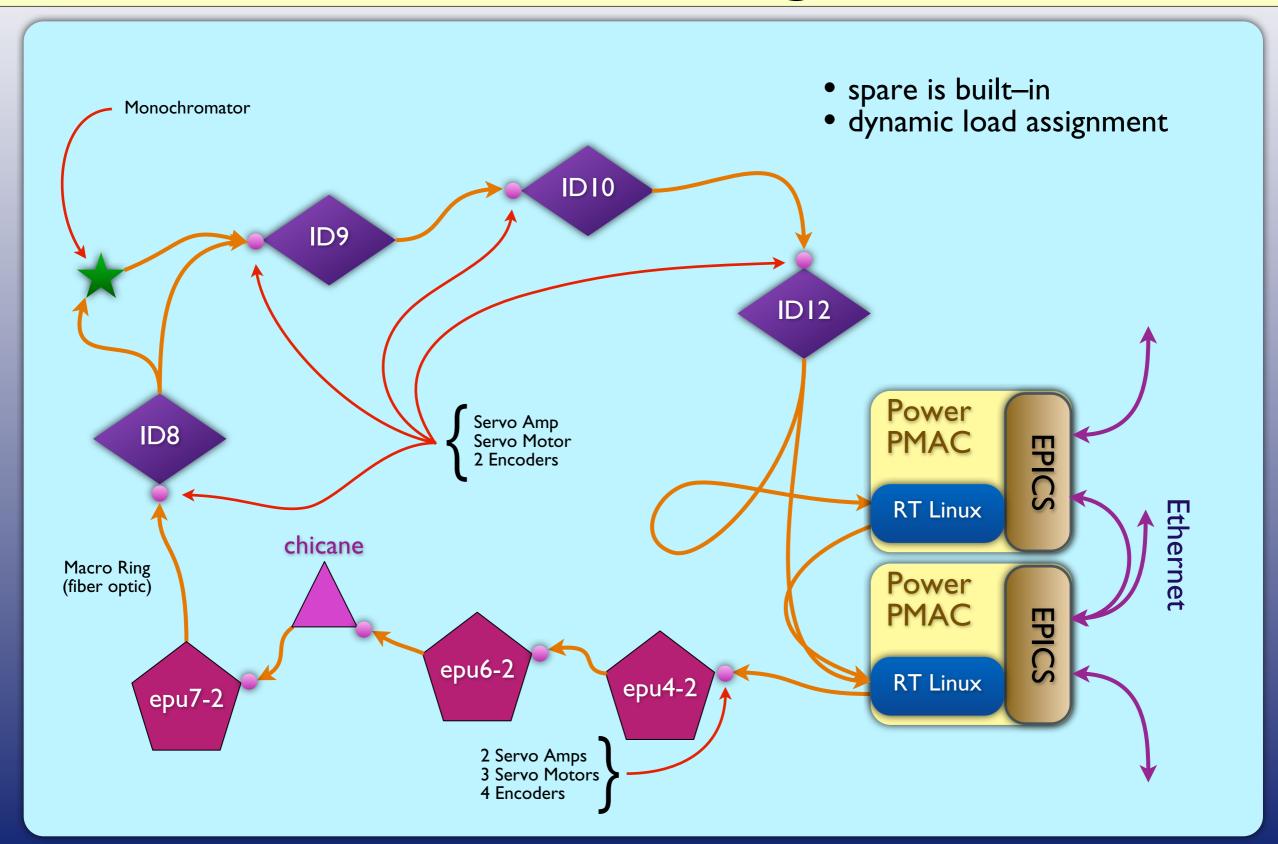
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Motorized Insertion Device Control at ALS





Power PMAC Configuration

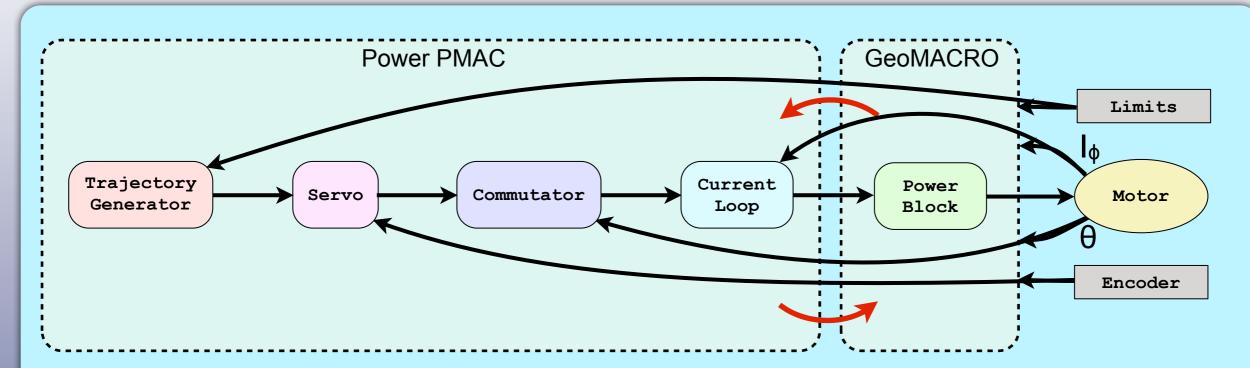








Controller / Amplifier



- The PMAC family of products provides components which distribute these functions in a variety of ways
- For ALS insertion device control, the PowerPMAC controller and GeoMACRO servo driver have been selected
- The Power PMAC and GeoMACRO are communicate via a fiber optic token ring, so may be located independently
- All motor connections (power, encoder, limit switches) are local, connected to the GeoMACRO which is mounted on the ID







Geo MACRO Drive

GATE ENABLE

Rotary sin-cos & absolute encoders

linear encoders

motor power

MACRO ring

limit switches

 $208~\mathrm{V}~3\phi \\ 24~\mathrm{VDC}$

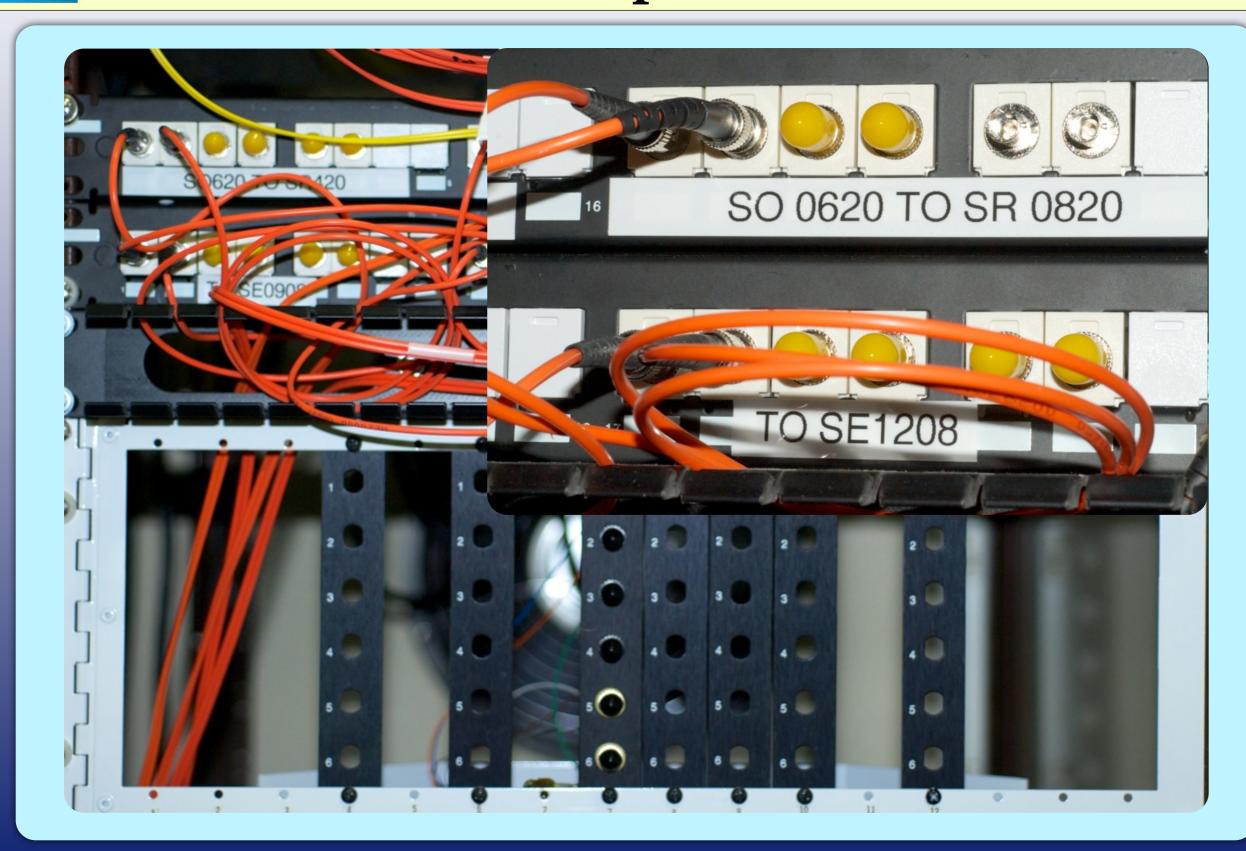






ALS

fiber panel









ALS

Glass Scale













Encoders

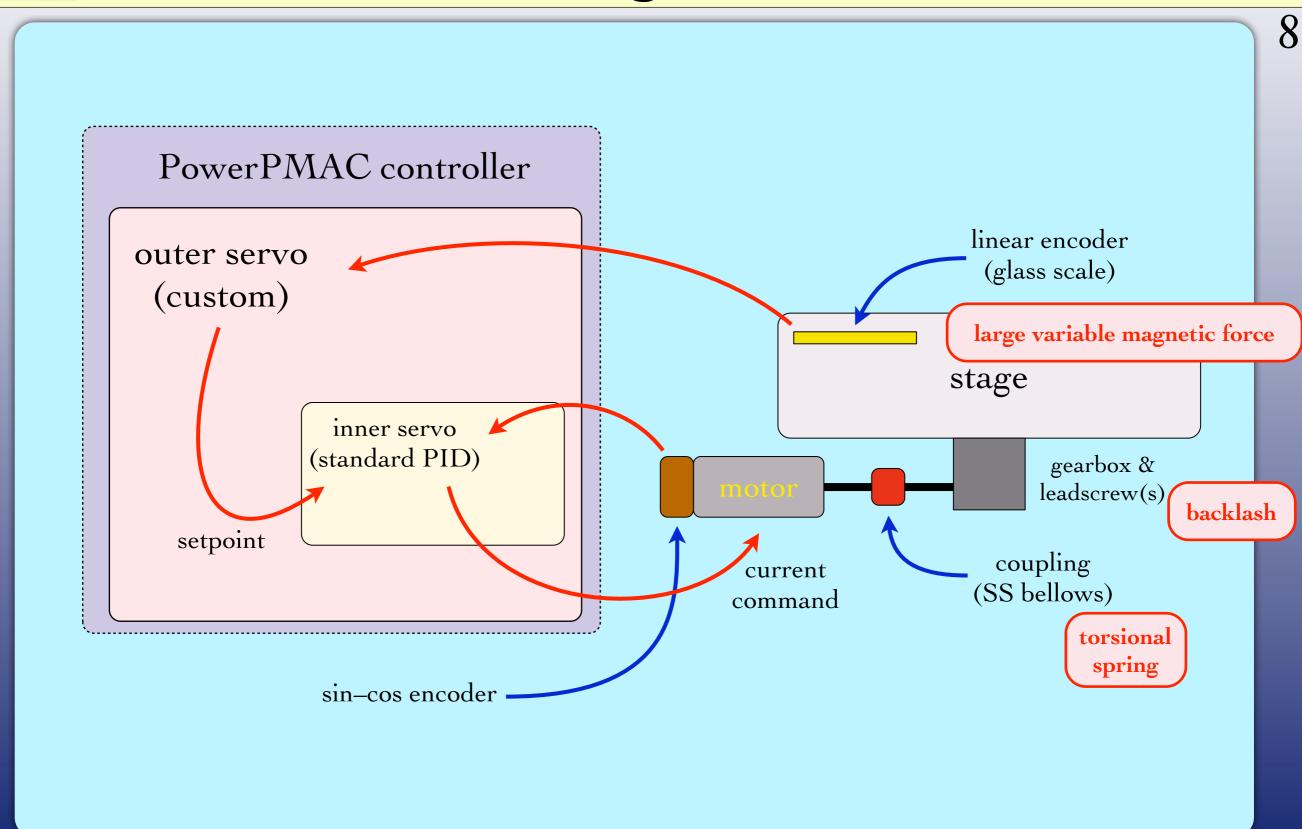
		Absolute (motor)	Rotary (motor)	Linear (stage)
Туре		Endat	Sin-Cos	Quadrature
Resolution (nm)	V	EPU: 19.5312 StdU: 16.2752	EPU: 2.4414 StdU: 0.5086	25 (2 encoders per stage)
	Н	48.8280	6.1035	50







Motor/Stage Control

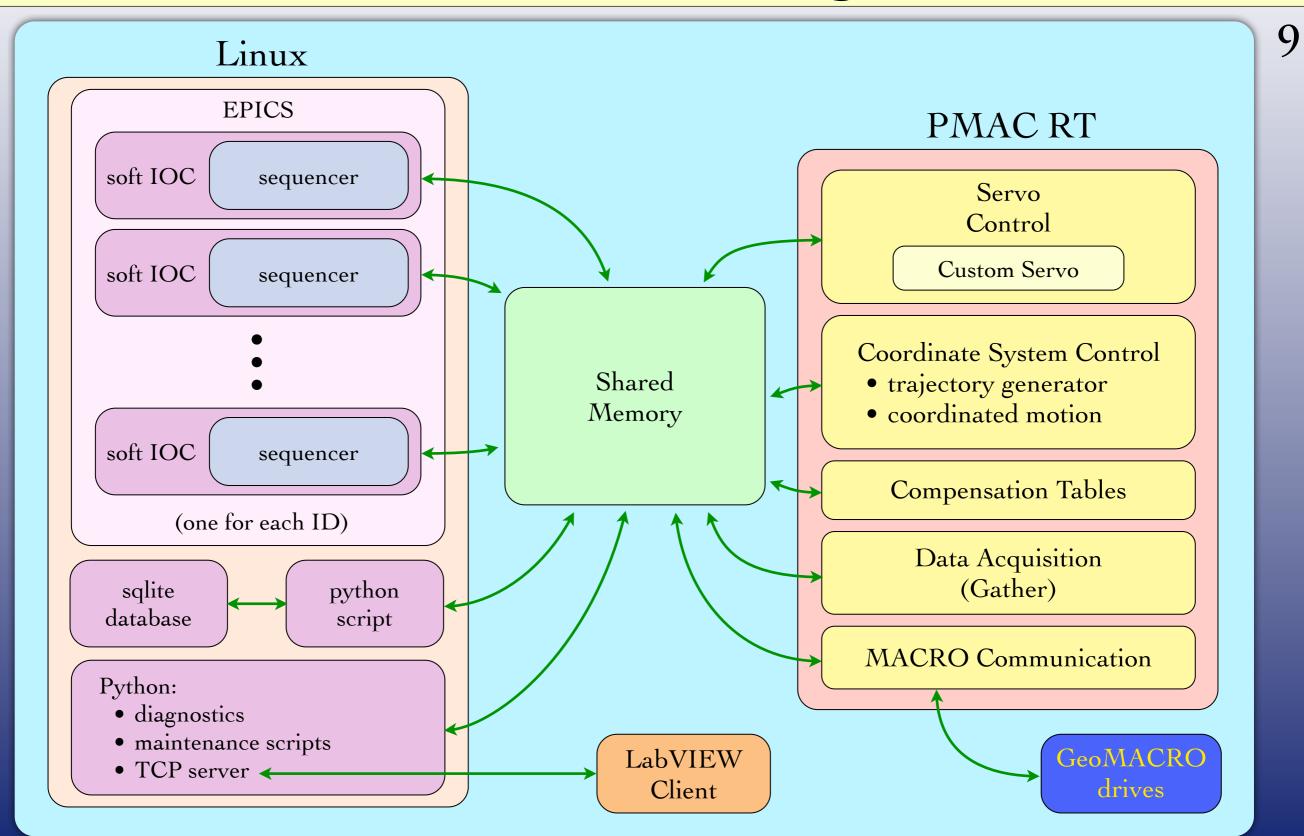








PPMAC Software Configuration

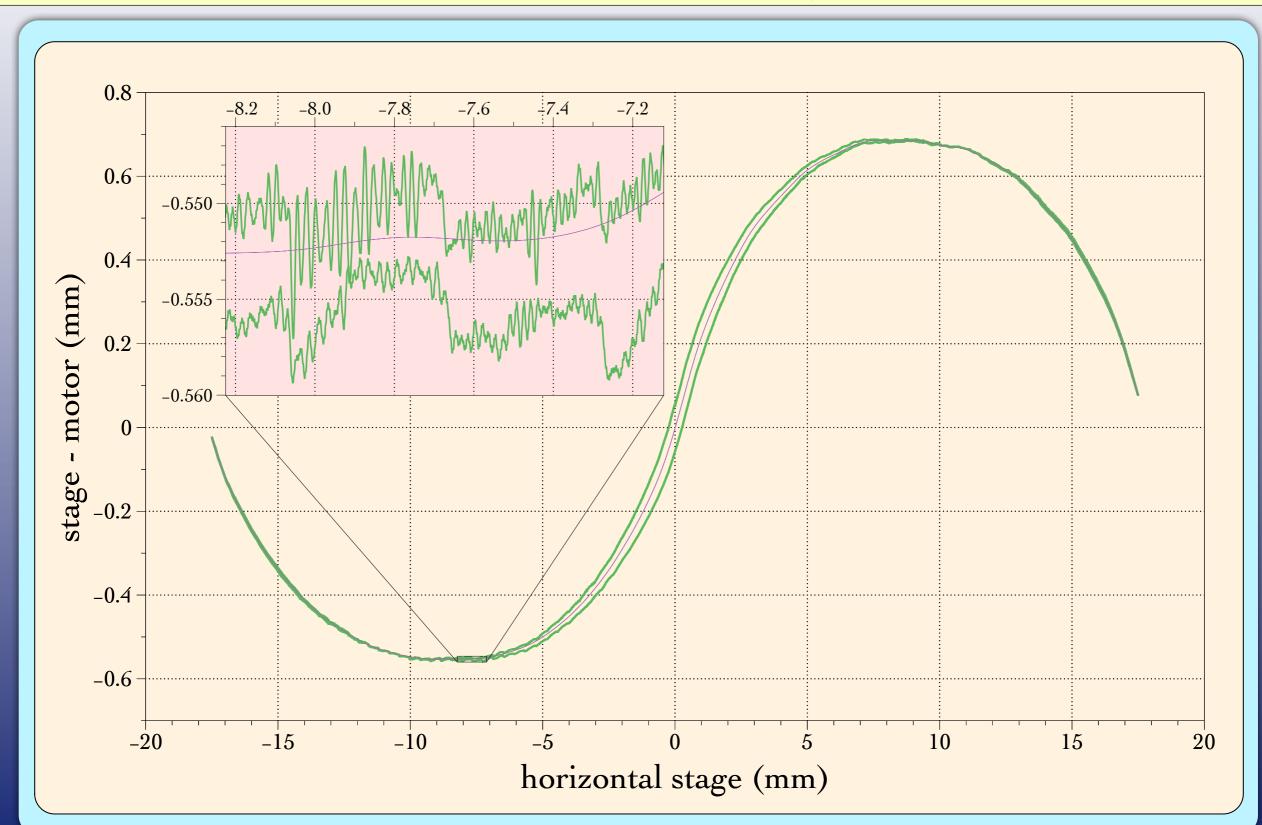








Horizontal Stage





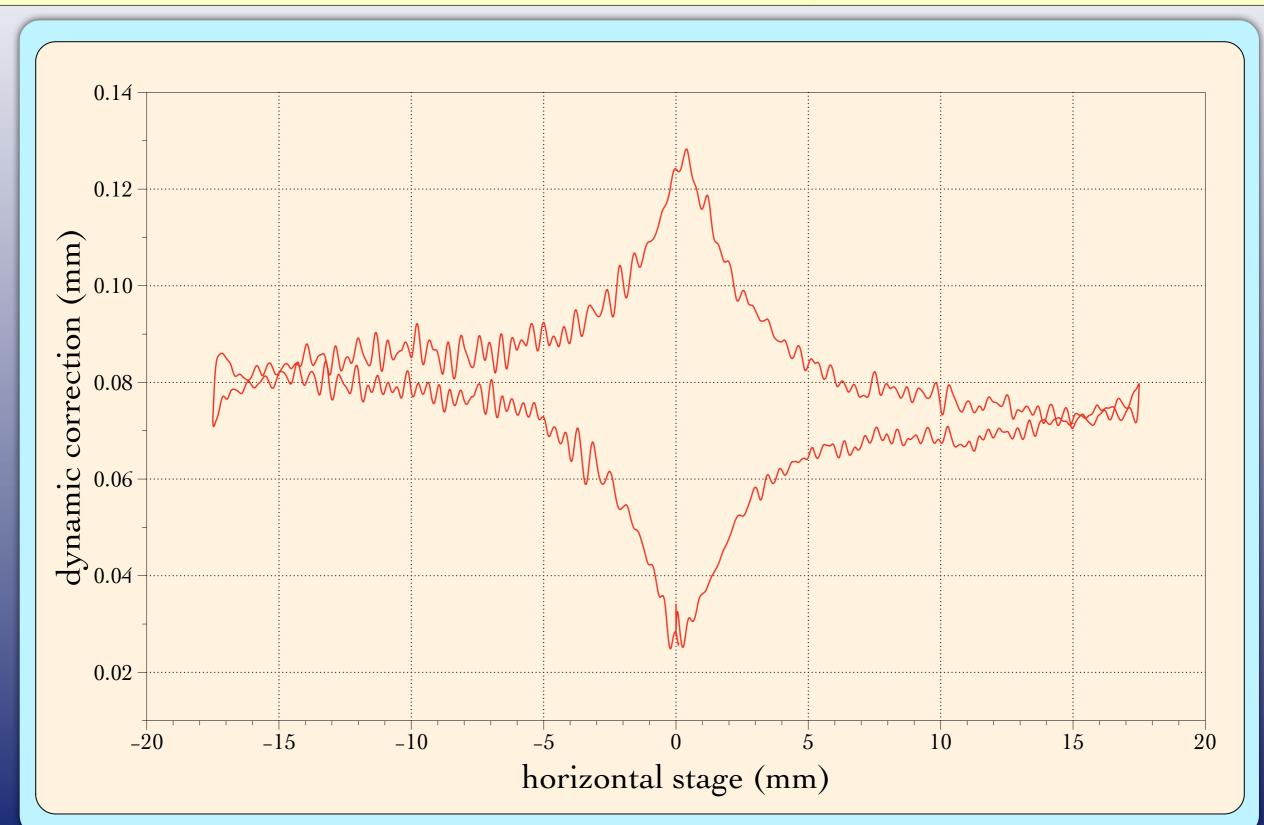




IO



Horizontal Stage



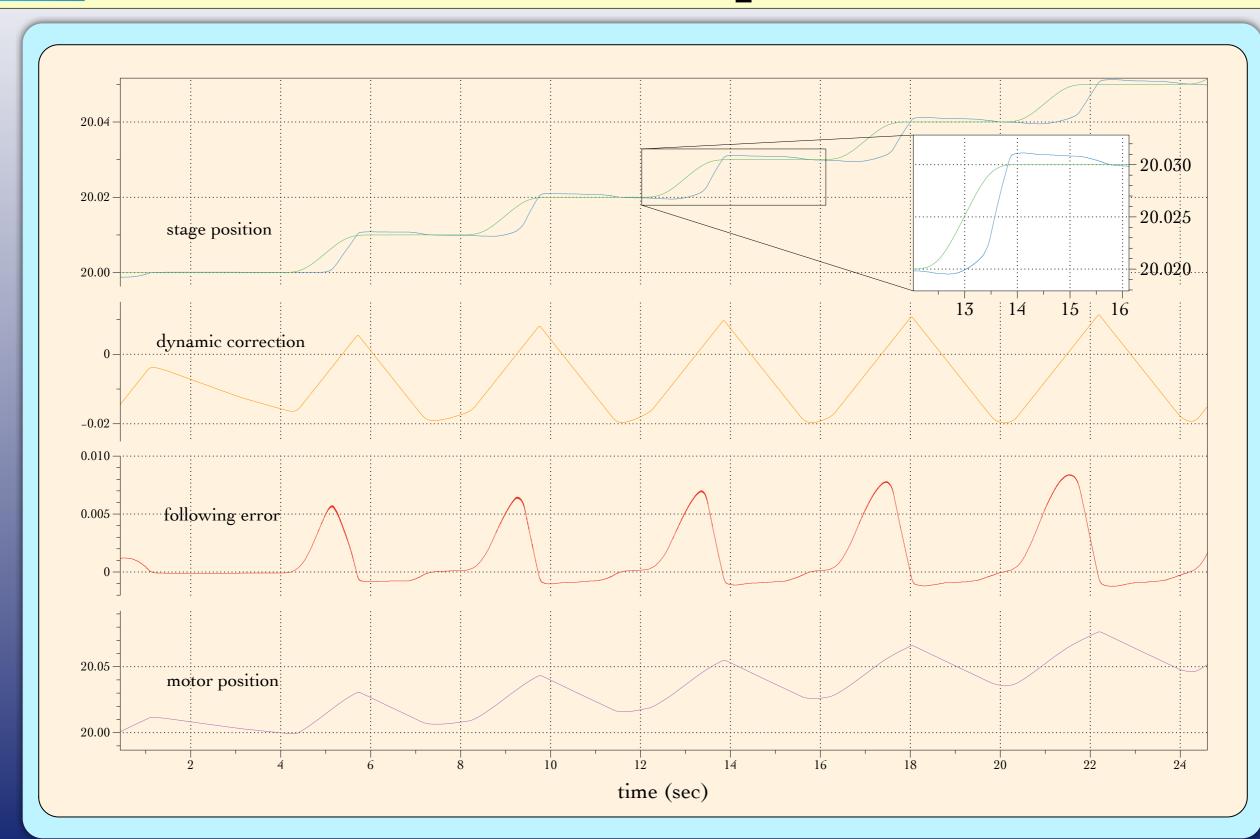






II

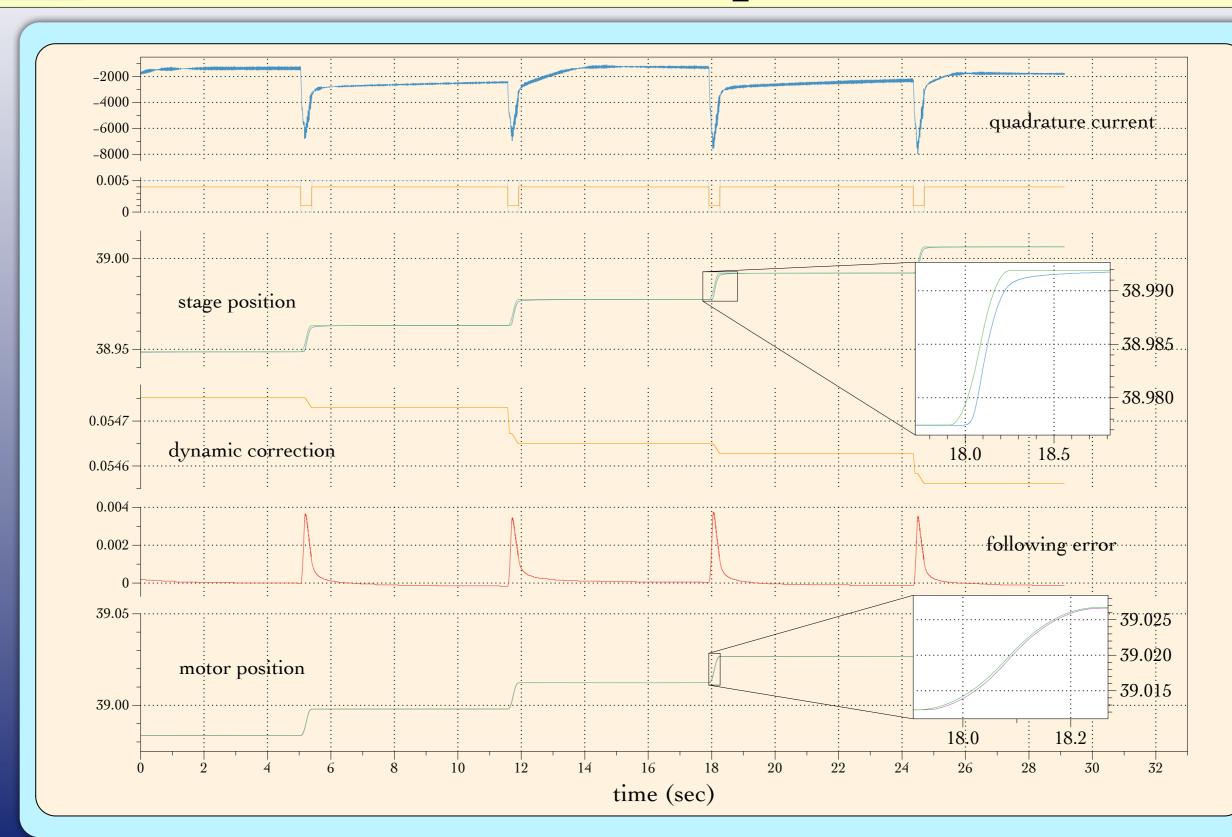
Small Steps







Small Steps









continuous limit

The fault trip

quadrature current

10000

1.5 µm steps

26.410

The fault trip

time (sec)





30

32

dynamic correction

following error



0.0120

0.0115

26.430

26.425

motor position